

# Richardson Extrapolation

There are many approximation procedures in which one first picks a step size  $h$  and then generates an approximation  $A(h)$  to some desired quantity  $A$ . Often the order of the error generated by the procedure is known. In other words

$$A = A(h) + Kh^k + O(h^{k+1}) \quad (1)$$

with  $k$  being some known constant,  $K$  being some other (probably unknown) constant and  $O(h^{k+1})$  designating any function that is bounded by a constant times  $h^{k+1}$  for  $h$  sufficiently small. For example,  $A$  might be the value  $y(t_f)$  at some final time  $t_f$  for the solution to an initial value problem  $y' = f(t, y)$ ,  $y(t_0) = y_0$ . Then  $A(h)$  might be the approximation to  $y(t_f)$  produced by Euler's method with step size  $h$ . In this case  $k = 1$ . If the improved Euler's method is used  $k = 2$ . If Runge-Kutta is used  $k = 4$ .

If we were to drop the, hopefully tiny, term  $O(h^{k+1})$  from equation (1), we would have one linear equation in the two unknowns  $A, K$ . We can get a second such equation just by using a different step size. Then the two equations may be solved, yielding approximate values of  $A$  and  $K$ . This approximate value of  $A$  constitutes a new improved approximation,  $B(h)$ , for the exact  $A$ . We do this now, taking  $h/2$  for the step size:

$$A = A(h/2) + K(h/2)^k + O(h^{k+1}) \quad (2)$$

and then  $2^k \cdot (2) - (1)$  gives:

$$\begin{aligned} (2^k - 1) A &= 2^k A(h/2) - A(h) + O(h^{k+1}) \\ \Rightarrow A &= \frac{2^k A(h/2) - A(h)}{2^k - 1} + O(h^{k+1}) \end{aligned}$$

Hence if we define

$$B(h) = \frac{2^k A(h/2) - A(h)}{2^k - 1} \quad (3)$$

then

$$A = B(h) + O(h^{k+1}) \quad (4)$$

and we have generated an approximation whose error is of order  $k+1$ , one better than  $A(h)$ 's. Similarly, by subtracting equation (2) from equation (1), we can find  $K$ .

$$0 = A(h) - A(h/2) + Kh^k \left(1 - \frac{1}{2^k}\right) + O(h^{k+1})$$

$$\Rightarrow K = \frac{A(h/2) - A(h)}{h^k \left(1 - \frac{1}{2^k}\right)} + O(h^{k+1})$$

Once we know  $K$  we can estimate the error in  $A(h/2)$  by

$$E(h/2) = A - A(h/2)$$

$$= K(h/2)^k + O(h^{k+1})$$

$$= \frac{A(h/2) - A(h)}{2^k - 1} + O(h^{k+1})$$

If this error is unacceptably large, we can use

$$E(h) \cong Kh^k$$

to determine a step size  $h$  that will give an acceptable error. This is the basis for a number of algorithms that incorporate automatic step size control.

Note that  $\frac{A(h/2) - A(h)}{2^k - 1} = B(h) - A(h/2)$ . One cannot get a still better guess for  $A$  by combining  $B(h)$  and  $E(h/2)$ .

### Example

$A = y(1) = 64.897803$  where  $y(t)$  obeys  $y(0) = 1$ ,  $y' = 1 - t + 4y$ .

$A(h)$  = approximate value for  $y(1)$  given by improved Euler with step size  $h$ .

$B(h) = \frac{2^k A(h/2) - A(h)}{2^k - 1}$  with  $k = 2$ .

h	$A(h)$	%	#	$B(h)$	%	#
.1	59.938	7.6	20	64.587	.48	60
.05	63.424	2.3	40	64.856	.065	120
.025	64.498	.62	80	64.8924	.0083	240
.0125	64.794	.04	160			

The “%” column gives the percentage error and the “#” column gives the number of evaluations of  $f(t, y)$  used.